

# STATISTICAL DETECTION OF DEFECTS IN RADIOGRAPHIC IMAGES OF WELDS

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**Abstract:** In this paper we investigate applicability of statistical techniques for defect detection in radiographic images of welds. The defect detection procedure consists in a statistical hypothesis testing using several nonparametric tests. A comparison of rules derived for image thresholding for a given level of false alarm is presented. In this work we consider longitudinal defects such as linear flaws similar to cracks. Numerical experiments with real and test data within MATLAB's abilities are performed.

**Introduction:** Film radiography is a traditional imaging inspection technique for nondestructive examination of industrial equipment components in order to locate any cavities, inclusions, lack of fusion and so on that may have been formed during the manufacturing or operation process [3,5]. Sophisticated image analysis of digitized films and digital radiographs is a widely studied research field, with much recent approaches using adaptive thresholding and probabilistic methods [1], neural networks [9], texture analysis [11], a wavelet-based multi-resolution image representation [15], a model-based statistical segmentation, mathematical morphology and pattern recognition. We refer to the works [2, 6, 7, and 13] where reviews with a comparative study of the methods can be found. The objective of this work is as follows: given a false alarm level, detect line-like defects in welds in realistic computer time. We try to investigate the possibilities of automatic image processing of weld defects with the help of statistical hypothesis testing using nonparametric statistical tests. We consider several tests which theoretically, for a given level of false alarm, provide us with a threshold resulting in a map of possible defects. The software is implemented in MATLAB and tested on images of welds of austenitic pipes acquired by radiography.

We consider the detection problem as a problem of hypothesis testing, in the most important practical formulation – the absence of a priori information about brightness distribution in the points of object and background. We assume that an image under investigation is inhomogeneous and anisotropic and all observed variables have continuous probability distribution functions. In case the image does not contain an object, we suggest that the observations are statistically independent. Let us define a shape of an investigated object by the form of the window (square, circular, longitudinal, etc.) which moves along the image. For each possible defect location, size and orientation of the window we investigate a problem of defect detection by testing the null hypothesis  $H_0$  : “Absence of a defect” against the alternative  $H_1$  : “Presence of the defect”. Rejection or acceptance of  $H_0$  is based on values of some test statistics computed within the sliding window. Hypothesis  $H_0$  is rejected when values of the statistics achieve a critical level (threshold).

**Results:** For each current pixel we choose longitudinal windows  $W_1$  and  $W_2$  with parameters  $R_1$  and  $R_2$  (Fig. 1). Let  $x_1, \dots, x_N$  be arbitrary pixel values from  $W_1$  and  $y_1, \dots, y_M$  be arbitrary pixels from  $W_2$ .

Denote  $x = \{x_i\}, i = 1, \dots, N$ ;  $y = \{y_j\}, j = 1, \dots, M$ . For detecting the object we test the null hypothesis  $H_0$  : “values  $x_i$  and  $y_j$  are stochastically equal” against the two – sided alternative hypothesis  $H_1$  : “ $x_i$  are stochastically larger (or less) than  $y_j$  “. For testing, we need appropriate statistics. We are going to test the hypothesis  $H_0$  with the use of statistics which do not depend on the form of the image brightness distribution functions unknown to the observer. Such statistics and the corresponding tests are often called nonparametric. *Sign Test:* One of the simplest nonparametric tests is a sign test [12]. Put  $M = N$  and assume that the pixels from the object are stochastically brighter (larger) than those from the background (one sided alternative). The Sign Criterion for testing the null hypothesis  $H_0$  is based on the following statistic:

$$v = \sum_{i=1}^N I\{x_i - y_i > 0\}, \quad (1)$$

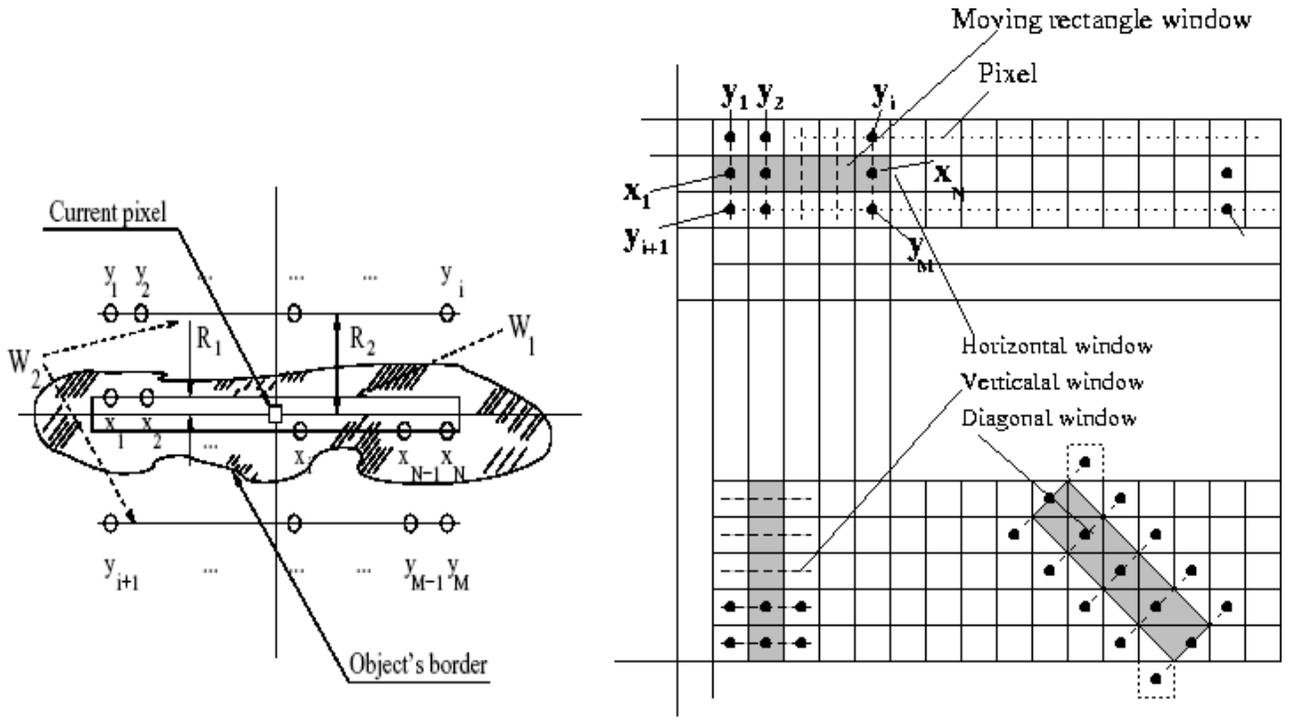


Figure 1: (Left) Longitudinal (horizontal) scheme of scanning. (Right) Image matrix with different orientations of scanning window.

That is the number of positive signs among  $x_1 - y_1, \dots, x_n - y_n$ . Here and in what follows, we define  $I\{A\} = 1$  if event  $A$  occurs and  $I\{A\} = 0$  if it does not. The sign test rejects the null hypothesis  $H_0$  when  $\nu \geq \lambda$ , where the threshold  $\lambda = \lambda(\alpha)$ , is determined by the acceptable level  $\alpha$  and equals the smallest integer such that

$$\sum_{i=\lambda}^N \binom{i}{N} 2^{-N} \leq \alpha. \quad (2)$$

*Rosenbaum Test:* As a second example, consider the Rosenbaum statistics [14]. Denote

$$A_1 = \text{the number of } x \text{ larger than } y_{\max} = \max\{y_j\}. \quad (3)$$

Given the integer  $r$ , it can be shown that the probability of event  $\{A_1 \geq r\}$  under the null hypothesis  $H_0$  has the form

$$\Pr(A_1 \geq r | H_0) = \frac{(N + M - r)! N!}{(M + N)! (N - r)!}. \quad (4)$$

The one-sided Rosenbaum test is as follows. Reject  $H_0$  only if  $A_1 \geq \lambda$ , where the threshold  $\lambda$  is the smallest integer such that

$$\frac{(N + M - \lambda)! N!}{(M + N)! (N - \lambda)!} \leq \alpha. \quad (5)$$

Let

$$A_2 = \text{the number of } y \text{ larger than } x_{\max} = \max\{x_i\}. \quad (6)$$

The two – sided Rosenbaum test for  $H_0$  against the two-sided alternative  $H_1$  is as follows. Reject  $H_0$  only if

$$T_1 \equiv A_1 - A_2 \geq C_1 \text{ or } T_1 \leq C_2.$$

Critical levels  $C_1$  and  $C_2$  depend upon the entire number  $Z$  of tests. In case of a single test, the probability of false alarm  $\Pr(A_1 \geq C_1 | H_0) + \Pr(A_2 \geq C_2 | H_0)$  is expressed as a ratio

$$\delta = \frac{(N + M - C_1)!N!}{(M + N)!(N - C_1)!} + \frac{(N + M - C_2)!M!}{(M + N)!(M - C_2)!}, \quad (7)$$

where  $C_1$  and  $C_2$  should be chosen so that the fractions in (7) are approximately the same and they are the smallest integers for which the relationship

$$\delta \leq \alpha \quad (8)$$

is hold.

If  $M = N$ , then  $C_1 = C_2$  and calculations are essentially simpler. In this case, given the probability of false alarm

$\alpha$  we reject the hypothesis  $H_0$  when  $|T_1| \geq C_1$ ,

where the threshold  $C_1$  is chosen as the smallest integer such that

$$2 \frac{(2N - C_1)!N!}{(2N)!(N - C_1)!} \leq \alpha. \quad (9)$$

*Haga Test:* The Rosenbaum test can be modified. Let

$B_1 =$  the number of  $y$  smaller than  $x_{\min}$ ,  $B_2 =$  the number of  $x$  smaller than  $y_{\min}$ .

Then the one – sided Haga test for  $H_0$  against the one – sided alternative  $H_1$  as is follows. Reject  $H_0$  only if

$A_1 + B_1 \geq C(\alpha)$ . The two - sided Haga test for  $H_0$  is to reject  $H_0$  if

$$T_2 = |A_1 + B_1 - A_2 - B_2| \geq C(\alpha/2). \quad (10)$$

Critical levels  $C(\alpha)$  and  $C(\alpha/2)$  can be taken from tables [4]

*Wilcoxon – Mann – Whitney test:* The following nonparametric test for  $H_0$  was originally proposed by Wilcoxon [16], Mann and Whitney [10]. The Mann - Whitney test is based on statistics

$$U^+ = \sum_{i=1}^N \sum_{j=1}^M I\{x_i - y_j > 0\},$$

$$U^- = \sum_{i=1}^N \sum_{j=1}^M I\{x_i - y_j < 0\}, \quad (11)$$

( $U^+ =$  number of pair  $\{x_i, y_j\}$  with  $x_i > y_j$ ). Values  $U^+$  and  $U^-$  are integers from 0 up to  $NM$  and distributed symmetrically near the point  $NM/2$  when  $H_0$  is true.

The Wilcoxon test is based on statistics

$$W = U^+ + \frac{1}{2}N(N+1). \quad (12)$$

Let the integer  $u > 0$  be fixed, and then the probability  $P(U^+ = u | H_0)(P(U^- = u | H_0))$  can be represented in the form

$$P(U^+ = u | H_0) = \frac{M!N!}{(M+N)!} \sum_{p(M)} 1, \quad (13)$$

where the summation is performed over all partitions  $p(M) = \{m_0, m_1, \dots, m_N\}$  of the number  $M$  into  $N+1$  integer nonnegative addenda's  $M = m_0 + m_1 + \dots + m_N$

satisfying the equality

$$\sum_{i=1}^N im_i = u. \quad (14)$$

The two – sided Mann – Whitney test for  $H_0$  against the two – sided alternative  $H_1$  is as follows. Reject  $H_0$  only if  $U^+ \geq C_U(\alpha/2)$  or  $U^- \geq C_U(\alpha/2)$ . The one – sided Mann – Whitney test to reject  $H_0$  if

$U^+ \geq C_U(\alpha)$ . The one – sided Wilcoxon test to reject  $H_0$  if  $W \geq C_w(\alpha)$ . In this work we use the two - sided Mann – Whitney test

$$U = \max\{U^+, U^-\}.$$

**Discussion:** In our preliminary numerical experiments, we used two ways of thresholding:

- 1) Blind or maximal thresholding, when only maximally possible values for test statistics are used. It means that we visualize only the objects that theoretically correspond to a minimal level of false alarm, i.e. extreme suspects on defect ness.
- 2) For a given level of false alarm we compute thresholds for different tests with fixed values of such processing parameters as  $M, N, R_1, R_2$  and  $Z$  (the entire number of all tests of hypothesis  $H_0$ ).

The experiments show that empirically chosen thresholds often are very close to the upper limit of the test statistic values. We show the result of detection by the Mann-Whitney test  $U$  thresholded by  $C=6525$  with parameters  $M=N=30, R_1=1, R_2=3$  in Figure 2. Choosing a value of the significance level  $\alpha$ , the user should take into account that this choice relates to the expectation of about  $\alpha Z$  defects. For instance, if the user intends to escape noisy false defects (but with a risk to miss a true defect), small values of  $\alpha$  have to be chosen. We can derive from the experiments that active and convenient interaction with computer and data is needed to tune statistical methods.

For this purpose, we use MATLAB (a product of the Math Works Inc.) as a means of running statistical detection experiments. MATLAB is a powerful platform for high - performance mathematical computation and graphical representation, whose basic element is an  $N$ -dimensional matrix. MATLAB provides a wide range of functions for use in data analysis, incorporates a programming language that is similar to many common languages such as FORTRAN, PASCAL and C, and enables a user to communicate with the computer through Graphical User Interface (GUI). The GUI created to accompany the defect detection experiments consists of a system of windows (a main window pictured in Figure 3). A GUI is a useful tool for dealing with thresholding problems and new defect detection approaches training.

**Conclusions:** The results presented here demonstrate that the methodology of hypothesis testing based on nonparametric statistics can be applied to problems of defect detection with some hope of success. The benefits in detection of sizes of the defects remain somewhat limited, although we do see images with reliably detected defective zones. Even unsupervised thresholding of the map of the investigated test statistics discloses the defects that are difficult to indicate by visual radiographic inspection.

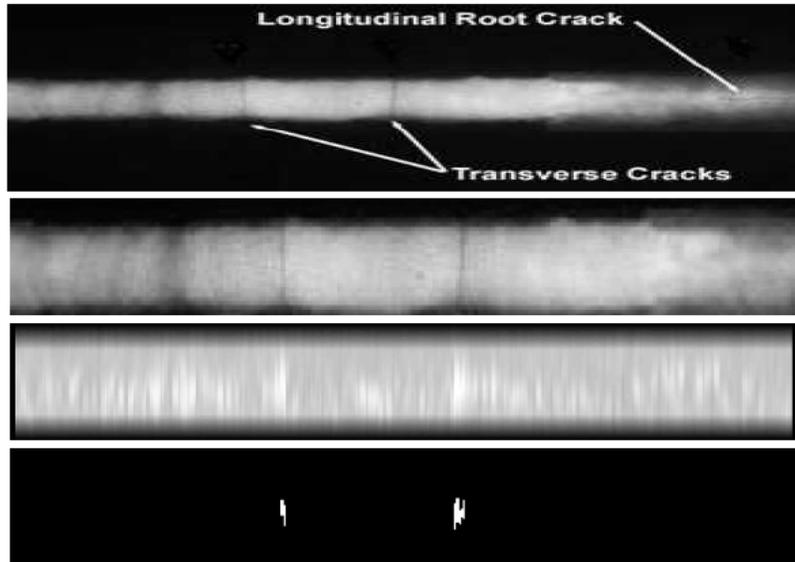


Figure 2: Image of 66 x 440 sizes with two transverse cracks; map of the Mann–Whitney test  $U$  statistic values thresholded by  $C = 6525$ , when maximal test value is  $C = 6700$ , for  $M = N = 30$ ,  $R_{\min} = 1$ ;  $R_2 = 3$ .

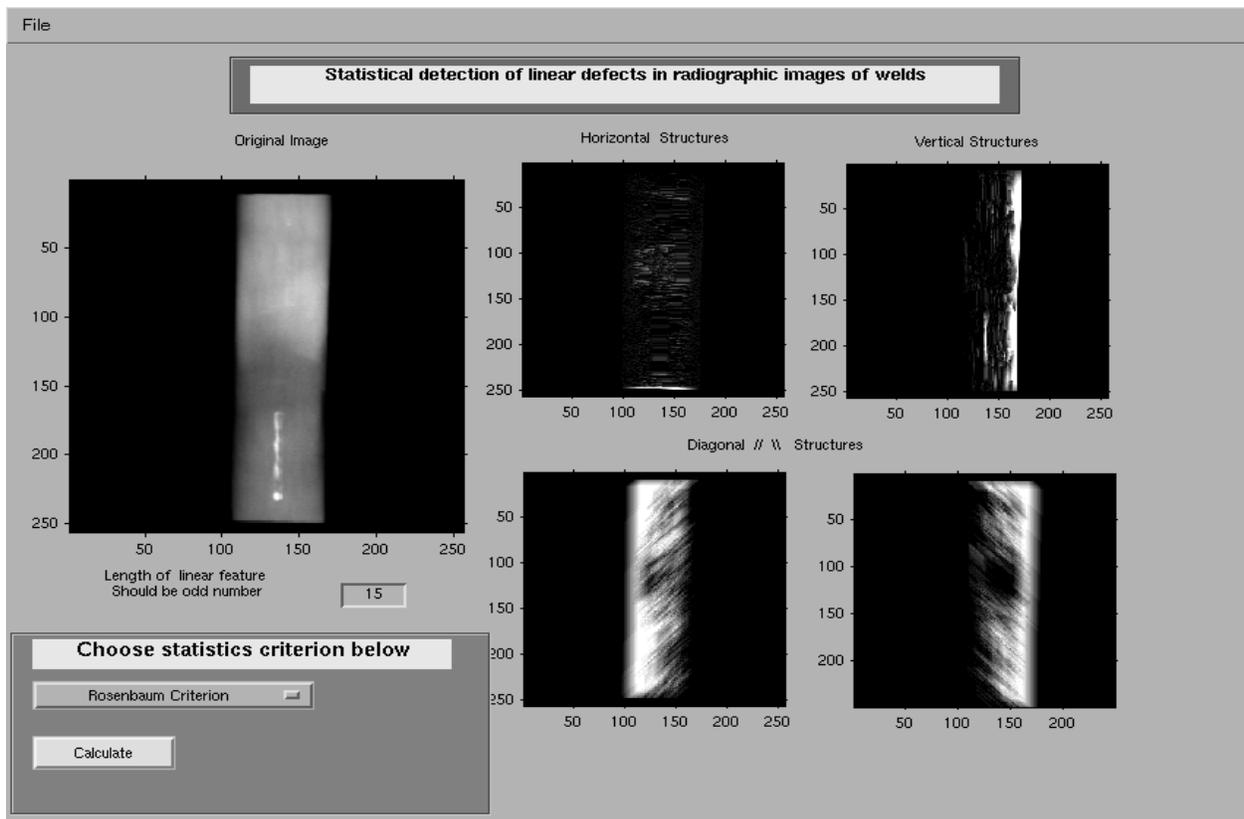


Figure 3: Main window of graphical user interface.

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